

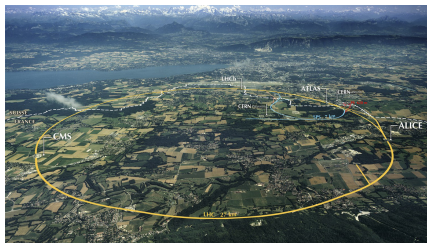
# Convolutional Neural Networks for Processing of ATLAS Liquid Argon Calorimeter Signals with FPGAs

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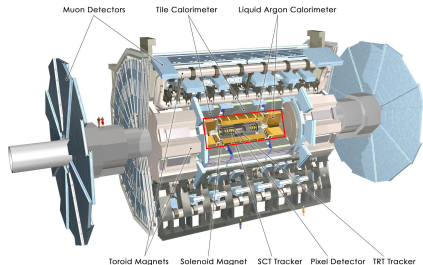
# The ATLAS Detector at the LHC



Source: [https://static1.bmbfcluster.de/3/4/3/8\\_ef6a5eef8f44963/3438meg\\_22ce2885dae52af.jpg](https://static1.bmbfcluster.de/3/4/3/8_ef6a5eef8f44963/3438meg_22ce2885dae52af.jpg)

## The Large Hadron Collider (LHC)

- 27 km circular collider at CERN/Geneva
- Accelerated proton bunches collide with 25 ns spacing (40 MHz)
- 2029: Start of **High Luminosity LHC** (HL-LHC) with 5 to 7.5 x nominal lumi



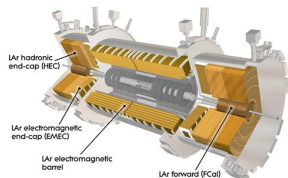
Source: The ATLAS Experiment at the CERN Large Hadron Collider, The ATLAS Collaboration et al, 2008 JINST 3 S08003

## The ATLAS Detector

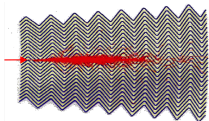
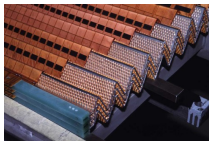
2026-2028: phase-2 upgrade

- Has to cope with **140-200 pile-up events** per collision
- Readout electronics of Liquid-Argon (LAR) calorimeters need to be improved

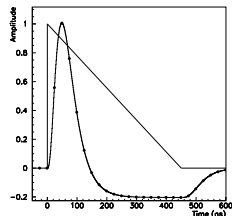
# Signal Readout of the ATLAS LAr Calorimeter



Source: <https://cds.cern.ch/record/1095928>



particle shower →



Source: The ATLAS Experiment at the CERN Large Hadron Collider, The ATLAS Collaboration et al, 2008 JINST 3 S08003

— readout per cell ↗

## LAr Calorimeter

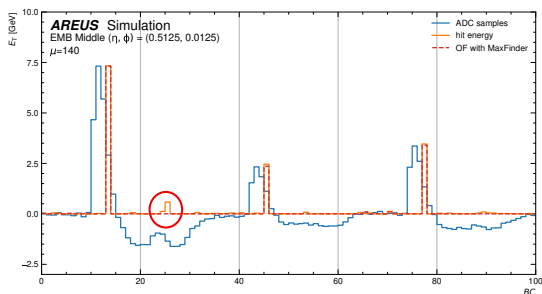
- Absorber material (Pb, Cu, W) and electrodes in accordion geometry
- In between **liquid argon** (→ LAr) as active medium

## Signals

- Energy deposits raise triangular pulse
- Shaped by  $CR(RC)^2$  analog filter into **bipolar pulse** and digitized
- Amplitude proportional to deposited energy
- Calculation in **realtime** by FPGAs

# The Current System

- **Optimal filtering** algorithm (**OF**) applied to calculate deposited energy per cell
- Optimized to suppress noise and to reconstruct peak timing
- Trigger system applies additional **maximum finder** ( $\rightarrow$  **OFMax**), is potentially insensitive during undershoot of pulse



$$y_t = \sum_{n=0}^{M-1} x_{t-n} \cdot a_n$$

$y_t$  ... OF output for bunch crossing (BC)  $t$

$\vec{x}$  ... input ADC samples

$a_n$  ... OF coefficients

$M$  ... OF filter depth



# Convolutional Neural Networks (CNNs)

- Convolutional operation with certain **filter/kernel** size
- **Activation function** gives opportunity to classify, weight, cut

$$y_t = A \left( \sum_{n=0}^2 x_{t-n} \cdot w_n + b \right)$$

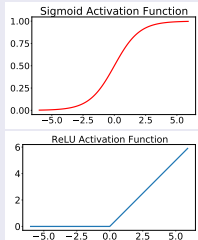
$y_t$  ... CNN output for bunch crossing (BC)  $t$

$\vec{x}$  ... input ADC samples

$w_t$  ... weights of kernel with size 3

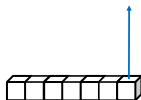
$b$  ... bias term

$A$  ... activation function



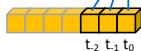
Output

Convolution ...



kernel=3

Input ...



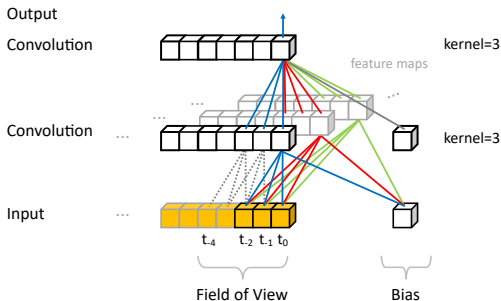
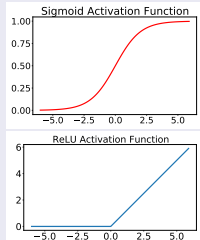
$t_2$   $t_1$   $t_0$



Bias

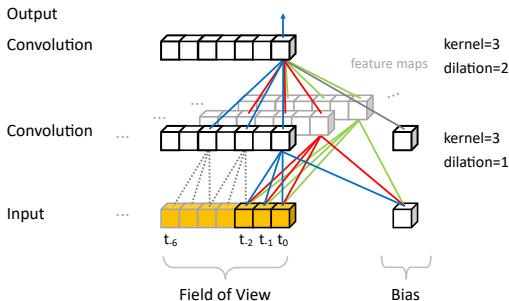
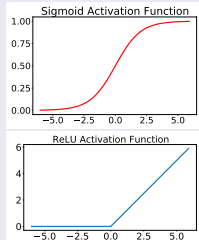
# Convolutional Neural Networks (CNNs)

- Convolutional operation with certain **filter/kernel** size
- **Activation function** gives opportunity to classify, weight, cut
- **Feature maps** focus on different properties
- **Training** minimizes difference between output and target



# Convolutional Neural Networks (CNNs)

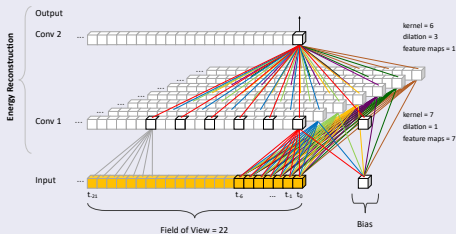
- Convolutional operation with certain **filter/kernel** size
- **Activation function** gives opportunity to classify, weight, cut
- **Feature maps** focus on different properties
- **Training** minimizes difference between output and target
- **Dilation** varies field of view (FOV) without increasing parameters
- Keep parameters low ( $\approx 100$ ) and FOV realistic ( $\approx 24$ ) since FPGA implementation planned



# Energy Reconstruction by CNNs

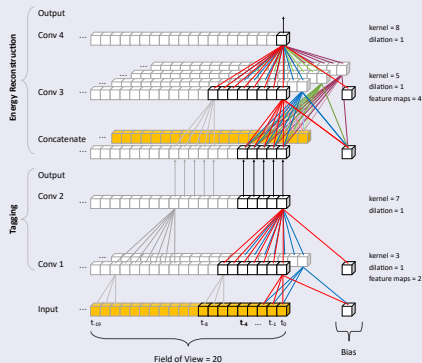
## Plain 2-layered CNN (2CNN)

- Input: digitized signals
- 2 layers ReLU activation function
- Uses dilation
- Output: reconstructed energy



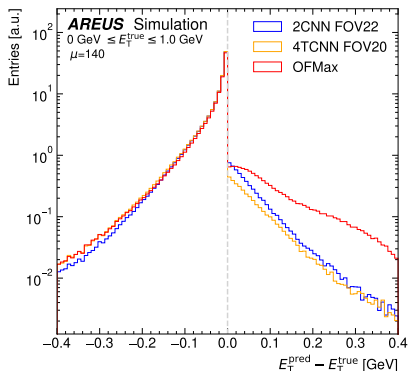
## 4-layered CNN with Tagging (4TCNN)

- Input: digitized signals
- 2 layers sigmoid activation function
- Intermediate output tags signals
- 2 layers ReLU activation function
- Output: reconstructed energy



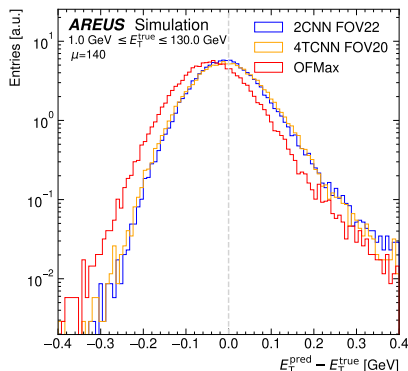
## Pile-up Energy Region

0 GeV - 1.0 GeV

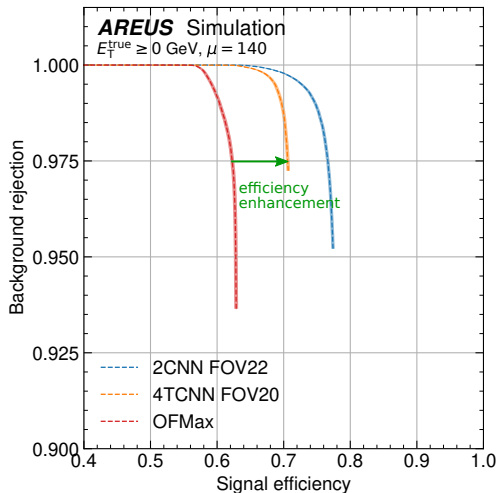


## Signal Energy Region

1.0 GeV - 130.0 GeV



- CNNs improve energy resolution especially in low energy region
- CNNs show smaller energy bias especially in high energy region

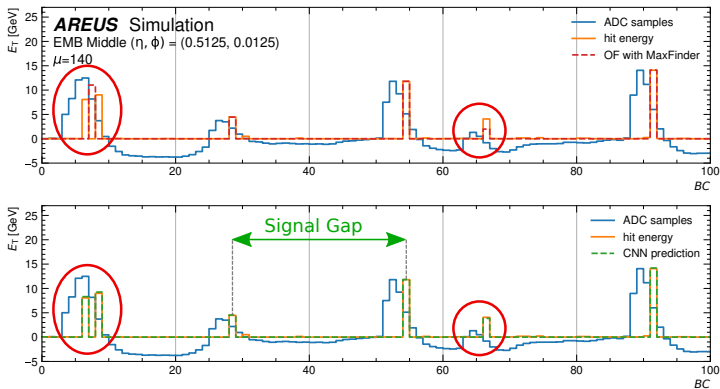


## Receiver Operating Characteristic (ROC) Curves

- Indicate detection performance
- Signal efficiency  
$$= \frac{\text{true positives}}{\text{true positives} + \text{false negatives}}$$
- Background rejection  
$$= \frac{\text{true negatives}}{\text{true negatives} + \text{false positives}}$$
- Dependent on threshold

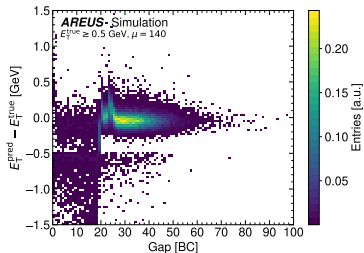
CNNs reach **higher signal efficiencies** at same background rejection level compared to OFMax

# Performance Evaluation: Influence of Overlapping Signals

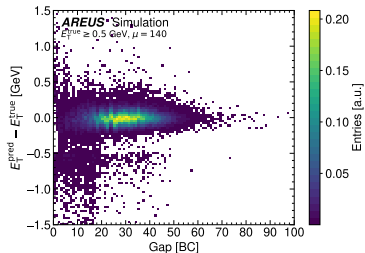


- New trigger accept scheme  $\rightarrow$  overlapping signals possible
- CNN optimized to reconstruct overlapping signals
- Performs well even with very close overlaps (BC6-8), when OF cannot resolve it

## Optimal Filter with Maximum Finder



## CNN with 2 Convolutional layers



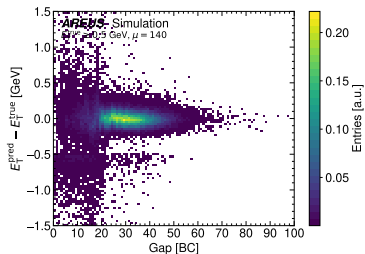
### OF

- Not able to resolve overlapping signals  $< 20$  BCs
- Shows artifact at BCs 20-25, at rising edge of pulse

### CNNs

- Much better overall performance
- Small offsets

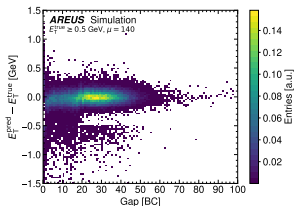
## TCNN with 4 Convolutional layers



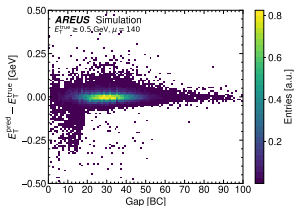


# Performance Evaluation: Different Detector Cells

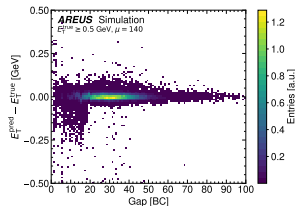
EMPresampler  $\eta = 0.0125$



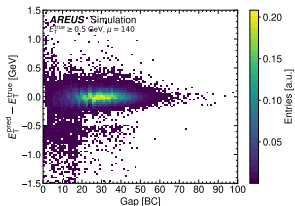
EMFront  $\eta = 0.5015625$



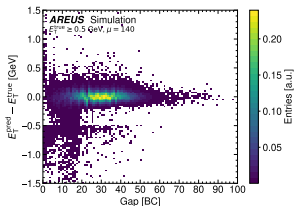
EMFront  $\eta = 1.0015625$



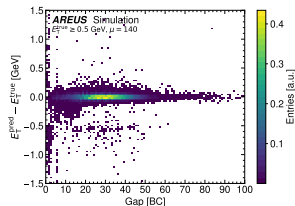
EMMiddle  $\eta = 0.5125$



EMMiddle  $\eta = 1.0125$

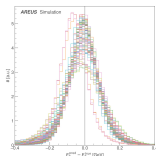


EMEC  $\eta = 2.0125$



Performance evaluation on different, representative detector cells show similar results

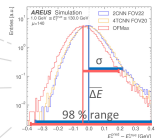
# Combining Performance Needs: Scoring of CNNs



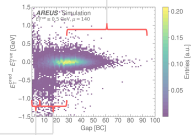
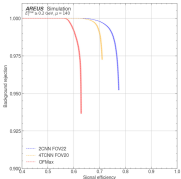
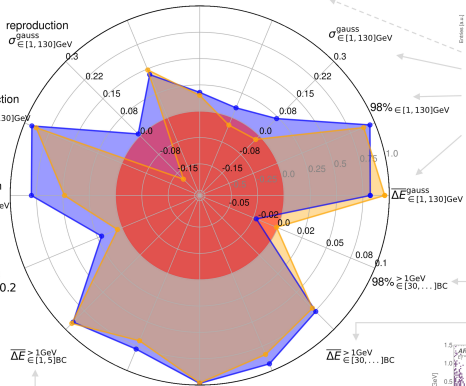
AREUS Simulation

98%  $\in [0.2, 1] \text{ GeV}$   
 $\Delta \bar{E} \in [0.2, 1] \text{ GeV}$

—●— 2CNN FOV22  
 —●— 4TCNN FOV20



- Score indicates performance
- Approaching outer circle (=1) is best
- Red circle indicates OFMax yield
- Crossing red circle: performance worse than OFMax



→ CNNs outperform OF for most parameters

## Convolutional Neural Networks ...

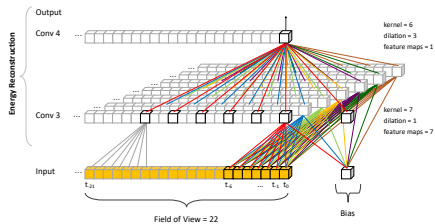
- Proved to be able to replace the Optimal Filtering algorithm
- Show better performance than the OF regarding energy resolution and signal efficiency, special benefit lies in detection and reconstruction of overlapping signals
- Application on different cells is consistent
- Evaluation with spider diagram enables to compare most important parameters
- Have small number of parameters ( $\approx 80-100$ ), so that FPGA resource limitations can be satisfied (see also talks by [Johann Voigt](#) and [Alexander Lettau](#))

**Thanks for your Attention!**

# Backup

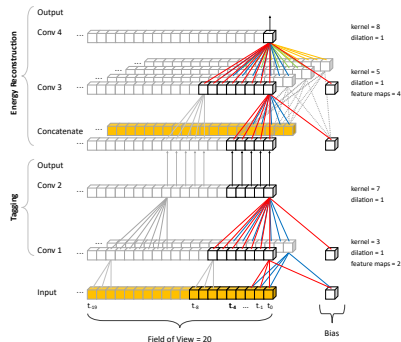
## 2CNN

kernel	[7,6]
feature maps	[7,1]
dilation	[1,3]
activation function	[ReLU, ReLU]

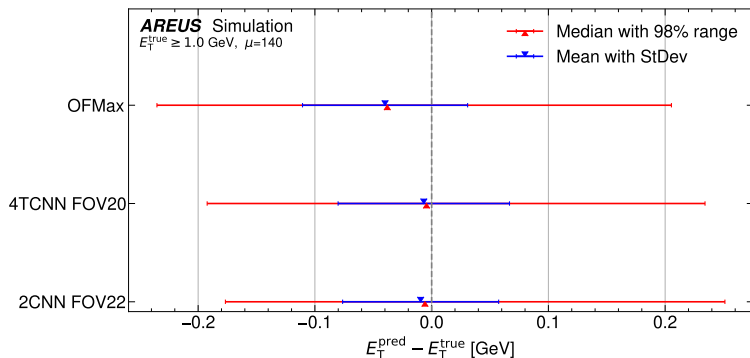


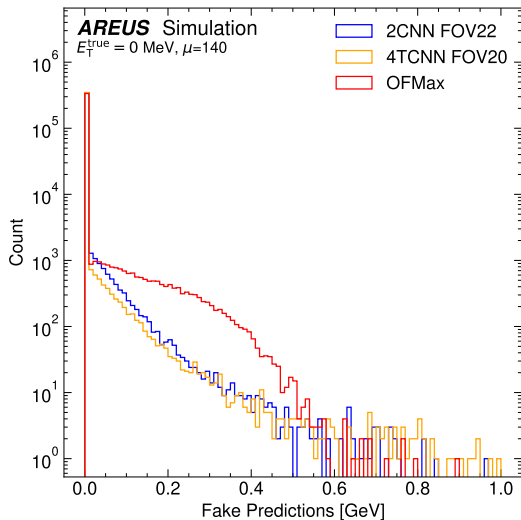
## 4TCNN

kernel	[3,7,5,8]
feature maps	[2,1,4,1]
dilation	[1,1,1,1]
activation function	[sig, sig, ReLU, ReLU]

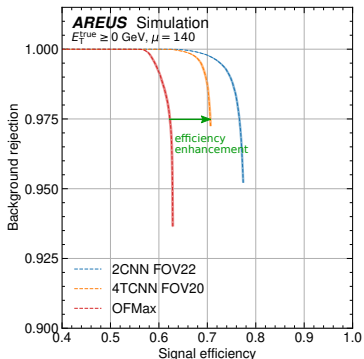
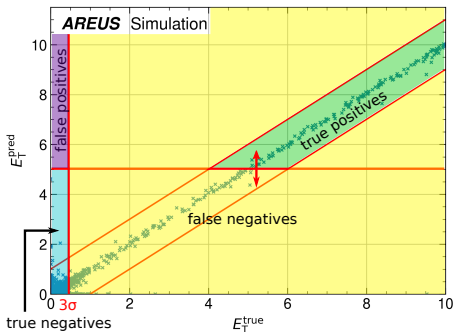


# Performance Evaluation: OF vs CNN - Energy Resolution





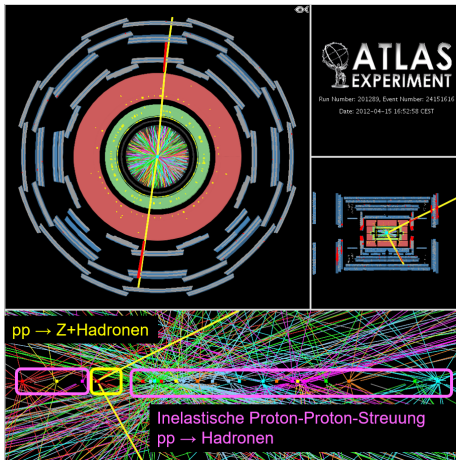
# ROC curves for CNNs



- declare everything above  $3\sigma$  electronic noise as signal
- exclude predictions with  $1 \text{ GeV} > E_{\text{true}} - E_{\text{pred}}$  to avoid counting bad energy reconstructions as true positives
- use largest rectangle (instead of integral) under the curve as score:

$$\text{score} = \frac{ROC_{\square}^{\text{ANN}} - ROC_{\square}^{\text{OFMax}}}{1 - ROC_{\square}^{\text{OFMax}}}$$





<https://iopscience.iop.org/article/10.1088/1742-6596/523/1/012018/pdf>